Introduction to hyperbolic groups

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Outline

- We discuss some basic notions of geometric group theory which are interesting in their own right and should be part of the general education of a mathematician.
- Parts of but not the entire material presented in this talk is relevant for the forthcoming talks.
- We will cover the following topics:
 - Quasi-isometry
 - Hyperbolic spaces
 - Hyperbolic groups
 - Some open problems about hyperbolic groups.

Definition (Quasi-isometry)

A map $f: X \to Y$ of metric spaces is called a quasi-isometry if there exist real numbers $\lambda, C > 0$ satisfying:

• The inequality

$$\lambda^{-1} \cdot d_X(x_1, x_2) - C \leq d_Y(f(x_1), f(x_2)) \leq \lambda \cdot d_X(x_1, x_2) + C$$

holds for all $x_1, x_2 \in X$;

• For every y in Y there exists $x \in X$ with $d_Y(f(x), y) < C$.

 The quasi-isometry condition may be summarized as being Lipschitz up to an additive constant.

Remark (Quasi-Isometry is an equivalence relation)

- If f: X₁ → X₂ is a quasi-isometry, then there exists a quasi-isometry g: X₂ → X₁ such that both composites g ∘ f and f ∘ g have bounded distance from the identity map.
- The composite of two quasi-isometries is again a quasi-isometry.
- Hence the notion of quasi-isometry is an equivalence relation on the class of metric spaces.

- The inclusion Z → R is an quasi-isometry. An inverse quasi-isometry R → Z is given by sending a real number r to the greatest integer which is less or equal to r.
- Quasi-isometries are not necessarily continuous.

Definition (Word-metric)

Let G be a finitely generated group. Let S be a finite set of generators. The word metric

 $d_S \colon G \times G \to \mathbb{R}$

assigns to (g, h) the minimum over all integers $n \ge 0$ such that $g^{-1}h$ can be written as a product $s_1^{\epsilon_1} s_2^{\epsilon_2} \dots s_n^{\epsilon_n}$ for elements $s_i \in S$ and $\epsilon_i \in \{\pm 1\}$.

Lemma

Let G be a finitely generated group. Let S_1 and S_2 be two finite sets of generators. Then the identity $id: (G, d_{S_1}) \rightarrow (G, d_{S_2})$ is a quasi-isometry.

Proof.

Choose λ such that for all $s_1 \in S_1$ we have $d_{S_2}(s_1, e), d_{S_2}(s_1^{-1}, e) \leq \lambda$ and for $s_2 \in S_2$ we have $d_{S_1}(s_2, e), d_{S_1}(s_2^{-1}, e) \leq \lambda$. Take C = 0.

Definition (Cayley graph)

Let *G* be a finitely generated group. Consider a finite set *S* of generators. The Cayley graph $\operatorname{Cay}_{S}(G)$ is the graph whose set of vertices is *G* and there is an edge joining g_1 and g_2 if and only if $g_1 = g_2 s^{\pm 1}$ for some $s \in S$.

On the next two slides we show the Cayley graph of Z with respect to the set of generators S = {1} and S = {2,3} and the Cayley graph of the free groups with two generators a and b.



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 A geodesic in a metric space (X, d) is an isometric embedding *I* → X, where *I* ⊂ ℝ is an interval equipped with the metric induced from the standard metric on ℝ.

Definition (Geodesic space)

A metric space (X, d) is called a geodesic space if for two points $x, y \in X$ there is a geodesic $c : [0, d(x, y)] \to X$ with c(0) = x and c(d(x, y)) = y.

 Notice that we do not require the unique existence of a geodesic joining two given points.

Remark (Metric on the Cayley graph)

- There is an obvious procedure to define a metric on Cay_S(G) such that each edge is isometric to [0,1] and such that the distance of two points in Cay_S(G) is the infimum over the length over all piecewise linear paths joining these two points.
- This metric restricted to G is just the word metric d_S and turns Cay_S(G) into a geodesic space.
- Obviously the inclusion (G, d_S) → Cay_S(G) is a quasi-isometry. In particular, the quasi-isometry class of the geodesic space Cay_S(G) is independent of S.
- The Cayley graph allows to translate properties of a finitely generated group to properties of a geodesic metric space and thus allows to use geometry to investigate groups.

Definition (Proper G-action)

A *G*-space *X* is called proper if for each pair of points *x* and *y* in *X* there are open neighborhoods V_x of *x* and W_y of *y* in *X* such that set $\{g \in G \mid gV_x \cap W_y \neq \emptyset\}$ is finite.

Definition (Cocompact G-action)

A *G*-space X is called cocompact if X/G is compact.

Lemma (Švarc-Milnor Lemma)

Let X be a geodesic space. Suppose that the finitely generated group G acts properly, cocompactly and isometrically on X. Choose a base point $x \in X$. Then the map

$$f: G \rightarrow X, \quad g \mapsto gx$$

is a quasi-isometry.

Definition (Commensurable)

Two groups G_1 and G_2 are commensurable if there are subgroups $H_1 \subseteq G_1$ and $H_2 \subseteq G_2$ such that the indices $[G_1 : H_1]$ and $[G_2 : H_2]$ are finite and H_1 and H_2 are isomorphic.

Lemma

Let G_1 and G_2 be finitely generated groups. Then:

- A group homomorphism G₁ → G₂ is a quasi-isometry if and only if its kernel is finite and its image has finite index in G₂;
- If G₁ and G₂ are commensurable, then they are quasi-isometric.

Example (Quasi-Isometry does not imply commensurable)

- Consider a semi-direct product G_φ = Z² ⋊_φ Z for an isomorphism φ: Z² → Z².
- These groups act properly and cocompactly by isometries on precisely one of the 3-dimensional simply connected geometries \mathbb{R}^3 , Nil or Sol.
- If ϕ has finite order, then the geometry is \mathbb{R}^3 .
 - If φ has infinite order and the eigenvalues of the induced C-linear map C² → C² have absolute value 1, then the geometry is Nil.
 - If ϕ has infinite order and one of the eigenvalues of the induced \mathbb{C} -linear map $\mathbb{C}^2 \to \mathbb{C}^2$ has absolute value > 1, then the geometry is Sol.
- These metric spaces given by the geometries ℝ³, Nil or Sol are mutually distinct under quasi-isometry.

Example (Continued)

- Two groups of the shape G_φ are quasi-isometric if and only if they belong to the same geometry.
- Two groups G_φ and G_{φ'} belonging to the same geometry ℝ³ or Nil are always commensurable.
- However, suppose that G_φ and G_{φ'} belong to Sol. Then they are commensurable if and only if the eigenvalues Λ and Λ' with absolute value > 1 of φ and φ', respectively, have a common power.
- This obviously yields examples of groups G_φ and G_{φ'} that belong to the geometry Sol and are quasi-isometric but are not commensurable.

Theorem (Group properties invariant under quasi-isometry)

The following properties of a group are quasi-isometry invariants:

- Finite;
- Infinite virtually cyclic;
- Finitely presented;
- Virtually abelian;
- Virtually nilpotent;
- Virtually free;
- Amenable;
- Hyperbolic;
- The existence of a model for the classifying space BG with finite n-skeleton for given n ≥ 2;
- The existence of a model for BG of finite type, i.e., all skeletons are finite.

Theorem (Invariants under quasi-isometry)

Let G_1 and G_2 be two finitely generated groups which are quasi-isometric. Then:

- They have the same number of ends;
- Let R be a commutative ring. Then we get

 $\operatorname{cd}_R(G_1)=\operatorname{cd}_R(G_2)$

if one of the following assumptions is satisfied:

- The cohomological dimensions cd_R(G₁) and cd_R(G₂) are both finite;
- One of the groups G_1 and G_2 is amenable and $\mathbb{Q} \subseteq R$;
- If they are solvable, then they have the same Hirsch length;

Theorem (Continued)

- Suppose that G₁ has polynomial growth of degree not greater than d, intermediate growth, or exponential growth, respectively. Then the same is true for G₂;
- Let G₁ and G₂ be nilpotent. Then their real cohomology rings H^{*}(G₁; ℝ) and H^{*}(G₂; ℝ) are isomorphic as graded rings. In particular the Betti numbers of G₁ and G₂ agree.

Remark (Free products)

- Let G₁, G'₁, G₂ and G'₂ be finitely generated groups. Suppose that G_i and G'_i are quasi-isometric for i = 1,2. Assume that none of the groups G₁, G'₁, G₂ and G'₂ is trivial or Z/2.
- Then the free products $G_1 * G_2$ and $G'_1 * G'_2$ are quasi-isometric.
- The corresponding statement is false if one replaces quasi-isometric by commensurable.

Remark (Property (T))

Kazhdan's Property (T) is not a quasi-isometry invariant.

Remark (The sign of the Euler characteristic)

The sign of the Euler characteristic of a group with a finite model for BG is not a quasi-isometry invariant.

Remark (L²-Betti numbers)

 If the finitely generated groups G₁ and G₂ are quasi-isometric and there exist finite models for BG₁ and BG₂ then we have

$$b_p^{(2)}(G_1)=0\Leftrightarrow b_p^{(2)}(G_2)=0.$$

• However, it is general not true that in the situation above there exists a constant C > 0 such that $b_p^{(2)}(G_1) = C \cdot b_p^{(2)}(G_2)$ holds for all $p \ge 0$.

Definition (Thin triangles)

A geodesic triangle in a geodesic space *X* is a configuration of three points x_1 , x_2 and x_3 in *X* together with a choice of three geodesics g_1 , g_2 and g_3 such that g_1 joins x_2 to x_3 , g_2 joins x_1 to x_3 and g_3 joins x_1 to x_2 . For $\delta > 0$ a geodesic triangle is called δ -thin if each edge is contained in the closed δ -neighborhood of the union of the other two edges.

Definition (Hyperbolic space)

Consider $\delta \ge 0$. A δ -hyperbolic space is a geodesic space whose geodesic triangles are all δ -thin.

A geodesic space is called hyperbolic it is δ -hyperbolic for some $\delta > 0$.



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- A geodesic space with bounded diameter is hyperbolic.
- A tree is 0-hyperbolic.
- The hyperbolic space \mathbb{H}^n is hyperbolic.
- More generally, a simply connected complete Riemannian manifold *M*, whose sectional curvature satisfies sec(*M*) ≤ κ for some κ < 0, is hyperbolic as a metric space.
- \mathbb{R}^n is hyperbolic if and only if $n \leq 1$.

Definition (Boundary of a hyperbolic space)

Let X be a hyperbolic space. Define its boundary ∂X to be the set of equivalence classes of geodesic rays. Put

 $\overline{X} := X \amalg \partial X.$

Two geodesic rays c₁, c₂: [0,∞) → X are called equivalent if there exists C > 0 satisfying d_X(c₁(t), c₂(t)) ≤ C for t ∈ [0,∞).

Lemma

There is a topology on \overline{X} with the properties:

- \overline{X} is compact and metrizable;
- The subspace topology $X \subseteq \overline{X}$ is the given one;
- X is open and dense in \overline{X} .

• Let *M* be a simply connected complete Riemannian manifold *M* with $\sec(M) \le \kappa$ for some $\kappa < 0$. Then *M* is hyperbolic as a metric space and $\partial M = S^{\dim(M)-1}$. The latter claim follows from the Cartan-Hadamard Theorem.

Lemma (Quasi-isometry invariance of being hyperbolic)

The property "hyperbolic" is a quasi-isometry invariant of geodesic spaces.

Lemma (Quasi-isometry invariance of the boundary)

A quasi-isometry $f\colon X_1\to X_2$ of hyperbolic spaces induces a homeomorphism

 $\partial X_1 \xrightarrow{\cong} \partial X_2.$

Definition (Hyperbolic group)

A finitely generated group is called hyperbolic if its Cayley graph is hyperbolic.

Definition (Boundary of a hyperbolic group)

Define the boundary ∂G of a hyperbolic group to be the boundary of its Cayley graph.

- A group *G* is hyperbolic if and only if it acts properly, cocompactly and isometrically on some hyperbolic space. In this case $\partial G = \partial X$.
- Let *M* be a closed Riemannian manifold with sec(M) < 0. Then $\pi_1(M)$ is hyperbolic with $S^{dim(M)-1}$ as boundary.
- If G is virtually torsionfree and hyperbolic, then vcd(G) = dim(∂G) + 1.
- If the boundary of a hyperbolic group contains an open subset homeomorphic to ℝⁿ, then the boundary is homeomorphic to Sⁿ.

• The boundary of a free group is a Cantor set.



 A typical boundary of a hyperbolic group looks like a Menger sponge which is a three-dimensional generalization of the one-dimensional Cantor set.



Remark (The boundary of a hyperbolic group)

- The boundary ∂X of a hyperbolic space and in particular the boundary ∂G of a hyperbolic group G are metrizable.
- Any compact metric space can be realized as the boundary of a hyperbolic space.
- However, not every compact metrizable space can occur as the boundary of a hyperbolic group.
- Namely, exactly one of the following three cases occurs:
 - G is finite and ∂G is empty;
 - G is infinite virtually cyclic and ∂G consists of two points;
 - G contains a free group of rank two as subgroup and ∂G is an infinite perfect, (i.e., without isolated points) compact metric space.

- A subgroup of a hyperbolic group is either virtually cyclic or contains Z ∗ Z as subgroup. In particular Z² is not a subgroup of a hyperbolic group.
- A free product of two hyperbolic groups is again hyperbolic.
- A direct product of two finitely generated groups is hyperbolic if and only if one of the two groups is finite and the other is hyperbolic.

Definition (Rips complex)

Let G be a finitely generated group generated by a finite set S of generators. For any $d \ge 0$ the simplicial complex $P_d(G, S)$, called the Rips complex, is defined as follows.

The vertices are elements of *G*. A finite collection of distinct elements g_0, g_1, \ldots, g_k in *G* spans a *k*-simplex if and only $d_S(g_i, g_j) \le d$ holds for all $0 \le i, j \le k$.

Theorem (Finiteness properties of hyperbolic groups)

Let G be a group with a finite set of generators.

- Suppose that (G, S) is δ-hyperbolic for the real number δ ≥ 0. Let d be a natural number with d ≥ 16δ + 8. Then the barycentric subdivision of the Rips complex P_d(G, S)' is a finite G-CW-model for <u>E</u>G;
- There is a model of finite type for BG, if G is hyperbolic;
- There is a finite model for BG, if G is torsionfree hyperbolic.

- A finitely generated torsion group is hyperbolic if and only if it is finite.
- Given *r* elements g₁, g₂, ..., g_r in a hyperbolic group, then there exists an integer n ≥ 1, such that {g₁ⁿ, g₂ⁿ, ..., g_rⁿ} generates a free subgroup of rank at most *r*.
- The word-problem and the conjugation-problem are solvable for a hyperbolic group.
- The isomorphism-problem is solvable for torsionfree hyperbolic groups.

- Let G be a hyperbolic group. Let S be a finite set of generators. For the integer n ≥ 0 let σ(n) be the number of elements g ∈ G with d_S(g, e) = n; Then the formal power series ∑_{n=0}[∞] σ(n) · tⁿ is a rational function.
- The same is true if one replaces σ(n) by the number β(n) of elements g ∈ G with d_S(g, e) ≤ n;
- A random finitely presented group is hyperbolic.

Remark (Construction of groups with exotic properties)

Colimits of directed systems of hyperbolic groups which come from adding more and more relations have been used to construct exotic groups. Here are two prominent examples:

- Let G be a torsionfree hyperbolic group which is not virtually cyclic. Then there exists a quotient of G which is an infinite torsion-group whose proper subgroups are all finite (or cyclic).
- There exist groups with expanders. They play a role in the construction of counterexamples to the Baum-Connes Conjecture with coefficients due to Higson, Lafforgue and Skandalis.

Some open problems about hyperbolic groups

- Is every hyperbolic group virtually torsionfree?
- Is every hyperbolic group residually finite?
- Cannon Conjecture: Suppose that the space at infinity of a hyperbolic group is homeomorphic to *S*². Does this imply that it acts properly isometrically and cocompactly on the 3-dimensional hyperbolic space?
- Has the boundary of a hyperbolic group the integral Čech cohomology of a sphere if and only if it occurs as the fundamental group of an aspherical closed manifold *M*?
- Is every hyperbolic group a CAT(0)-group?
- Is the complex group ring CG of a torsionfree hyperbolic group an integral domain?

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